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A Minimalistic Approach to Swimming Through Sand MATT BZDEGA, TRISTEN DENNEN, Emory University, STEPHAN KOEHLER, Emory University Physics Department — Inspired by microorganisms swimming at low Reynolds, we are interested in understanding how self-propelled robots can swim through sand. We find that a two-hinged swimmer can propel itself forwards and backwards through a simple sequence of cyclically repeated stroking motions. A range of parameters including paddle size, shape, and stroking angles, along with variations of the swimming strategies were investigated and the results show similarities to Purcell's two-hinged swimmer.

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