

Abstract Submitted  
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**Magnetic Field Assisted Milli-scale Robotic Assembly Machine:  
An Approach to Massively Parallel Robotic Automation Systems** YAN  
LIU, NUGGEHALLI RAVINDRA, New Jersey Inst of Tech — Using large numbers  
of micro robots to heterogeneously integrate small pieces to build advanced struc-  
tures has long been a vision in manufacturing automation. In this paper, a new  
type of machine, Magnetic Field Assisted Milli-scale Robotic Assembly machine is  
described. The machine prototype consists of a 16x16 array of electromagnets. We  
have successfully demonstrated using the machine to manipulate up to 9 milli-scale  
robots simultaneously. Moreover, we have demonstrated pick-and-place 2 LEDs si-  
multaneously by operating two micro robots. The design and modeling of the micro  
robot are also discussed.

Yan Liu  
New Jersey Inst of Tech

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