

Abstract Submitted  
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**Resistive force theory for sand swimming** YANG DING, School of Physics, Georgia Tech, RYAN MALADEN, Bioengineering Program, Georgia Tech, CHEN LI, DANIEL GOLDMAN, School of Physics, Georgia Tech — We discuss a resistive force theory<sup>1</sup> that predicts the ratio of forward speed to wave speed (wave efficiency,  $\eta$ ) of the sandfish lizard as it swims in granular media of varying volume fraction  $\phi$  using a sinusoidal traveling wave body motion. In experiment  $\eta \approx 0.5$  independent of  $\phi$  and is intermediate between  $\eta \approx 0.2$  for low  $Re$  Newtonian fluid undulatory swimmers like nematodes and  $\eta \approx 0.9$  for undulatory locomotion on a deformable surface. To predict  $\eta$  in granular media, we developed a resistive force model which balances thrust and drag force over the animal profile. We approximate the drag forces by measuring the force on a cylinder (a “segment” of the sandfish) oriented at different angles relative to the displacement direction. The model correctly predicts that  $\eta$  is independent of  $\phi$  because the ratio of thrust to drag is independent of  $\phi$ . The thrust component of the drag force is relatively larger in granular media than in low  $Re$  fluids, which explains why  $\eta$  in frictional granular media is greater than in viscous fluids.

<sup>1</sup>Maladen et. al, Science, **325**, 314, 2009

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